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ON M-PROJECTIVE CURVATURE TENSOR OF SASAKIAN MANIFOLDS ADMITTING ZAMKOVOY CONNECTION

ABHIJIT MANDAL¹ AND ASHOKE DAS

ABSTRACT. The purpose of the present paper is to study some properties of Sasakian manifold admitting Zamkovoy connection. We study M-Projectively flat, as well as $\phi - M$ -Projectively flat Sasakian manifolds admitting Zamkovoy connection. Moreover, we discuss locally M-Projectively ϕ -symmetric Sasakian manifold with respect to Zamkovoy connection. Besides these, we discuss Sasakian manifolds satisfying $\overline{M}(\xi, U) \circ \overline{R} = 0$, where \overline{M} and \overline{R} are M-Projective curvature tensor and Riemannian curvature tensor with respect to Zamkovoy connection respectively.

1. INTRODUCTION

The notion of Sasakian structure [12] was introduced by Japanese mathematician S. Sasaki in the year 1960. If a contact metric manifold is normal then the manifold is said to be a Sasakian manifold. In some respect, Sasakian manifolds may be viewed as an odd dimensional analogues of Kâhler manifolds.

In 1971, Pokhariyal and Mishra [9] introduced the notion of M-Projective curvature tensor on Riemannian manifold. Properties of the M-projective curvature tensor in Sasakian manifolds were studied by R.H. Ojha [7]. Also, in [11], R.H. Ojha studied some properties of M-Projective curvature tensor in

¹corresponding author

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Sasakian manifolds and showed that a M-Projective recurrent Sasakian manifold is M-Projectively flat iff it is an Einstein manifold. This curvature tensor was further studied by many authors. For instance, see ([5,6,8,10,14]). The M-Projective curvature tensor of rank 3 is given by

(1.1)
$$M(X,Y) Z = R(X,Y) Z - \frac{1}{2(n-1)} [S(Y,Z) X - S(X,Z) Y] - \frac{1}{2(n-1)} [g(Y,Z) QX - g(X,Z) QY]$$

for all $X, Y, Z \in \chi(\mathbf{M})$, set of all vector fields of manifold \mathbf{M} , where R(X, Y) Z is the Riemannian curvature tensor of type (0,3), S denotes the Ricci tensor of type (0,2) and Q denotes Ricci operator.

In 2008, The notion of Zamkovoy connection was introduced by S. Zamkovoy [17] for a paracontact manifold. And this connection was defined as a canonical paracontact connection whose torsion is the obstruction of paracontact manifold to be a para Sasakian manifold. For an *n*-dimensional almost contact metric manifold M equipped with an almost contact metric structure (ϕ, ξ, η, g) consisting of a (1, 1) tensor field ϕ , a vector field ξ , a 1-form η and a Riemannian metric *g*, the Zamkovoy connection is defined by

(1.2)
$$\overline{\nabla}_{X}Y = \nabla_{X}Y + (\nabla_{X}\eta)(Y)\xi - \eta(Y)\nabla_{X}\xi + \eta(X)\phi Y$$

for all $X, Y \in \chi(\mathbf{M})$. This connection was further studied by A.M. Blaga [3] in para Kenmotsu manifolds and A. Biswas, K.K. Baishya ([1, 2]) in Sasakian manifolds.

In a Sasakian manifold M of dimension n > 2, the *M*-projective curvature tensor \overline{M} with respect to the Zamkovoy connection $\overline{\nabla}$ is given by

(1.3)
$$\overline{M}(X,Y)Z = \overline{R}(X,Y)Z - \frac{1}{2(n-1)} \left[\overline{S}(Y,Z)X - \overline{S}(X,Z)Y\right] - \frac{1}{2(n-1)} \left[g(Y,Z)\overline{Q}X - g(X,Z)\overline{Q}Y\right]$$

where \overline{R} , \overline{S} and \overline{Q} are Riemannian curvature tensor, Ricci tensor and Ricci Operator with respect to Zamkovoy connection $\overline{\nabla}$ respectively.

Definition 1.1. An *n*-dimensional Sasakian manifold M is said to be η -Einstein manifold if the Ricci tensor is of the form: $S(X,Y) = k_1g(X,Y) + k_2\eta(X)\eta(Y)$, for all $X, Y \in \chi(\mathbf{M})$, where k_1 and k_2 are scalars.

Definition 1.2. An *n*-dimensional Sasakian manifold M is said to be M-projectively flat if the *M*-Projective curvature tensor vanishes identically (that is, $\overline{M} = 0$).

Definition 1.3. An *n*-dimensional Sasakian manifold **M** is said to be $\phi - M$ -projectively flat if $g(\overline{M}(\phi X, \phi Y) \phi Z, \phi V) = 0$ for all X, Y, Z and $V \in \chi(\mathbf{M})$.

Definition 1.4. An *n*-dimensional Sasakian manifold **M** is said to be $\xi - M$ -projectively flat if $\overline{M}(X, Y) \xi = 0$ for all $X, Y \in \chi(\mathbf{M})$.

This paper is organised as follows:

After introduction, a short description of Sasakian manifold is given in Section 2. In Section 3, we have discussed Sasakian manifold admitting Zamkovoy connection $\overline{\nabla}$ and obtained Riemannian curvature tensor \overline{R} , Ricci tensor \overline{S} , Scalar curvature tensor \overline{r} , Ricci operator \overline{Q} with respect to Zamkovoy connection. In Section 4, we have discussed M-Projectively flat Sasakian manifold with respect to the connection. In Section 5, we have discussed $\phi - M$ -Projectively flat Sasakian manifold with respect to Zamkovoy connection. In Section 6, we have discussed locally M-Projectively ϕ -symmetric Sasakian manifold. In Section 7, we have discussed Sasakian manifold satisfying $\overline{M}(\xi, U) \circ \overline{R} = 0$. Finally, Section 8 contains a 5-dimensional Sasakian manifold admitting Zamkovoy connection.

2. PRELIMINARIES

Let M be an *n*-dimensional almost contact metric manifold equipped with an almost contact metric structure (ϕ, ξ, η, g) consisting of a (1, 1) tensor field ϕ , a vector field ξ , a 1-form η and a Riemannian metric *g* satisfying

$$\begin{split} \phi^{2}Y &= -Y + \eta(Y)\xi, \eta(\xi) = 1, \eta(\phi X) = 0, \ \phi\xi = 0\\ g(\phi X, \phi Y) &= g(X, Y) - \eta(X)\eta(Y)\\ g(X, \phi Y) &= -g(\phi X, Y), \eta(Y) = g(Y, \xi), \forall X, Y \in \chi(\mathbf{M}) \,. \end{split}$$

Then, the almost contact metric manifold M is said to be a contact metric manifold if $g(X, \phi Y) = d\eta(X, Y), \forall X, Y \in \chi(\mathbf{M})$.

Also, a contact manifold M is said to be Sasakian manifold if the following conditions hold:

(2.1)
$$\nabla_X \xi = -\phi X, (\nabla_X \phi) Y = g(X, Y) \xi - \eta(Y) X$$
$$R(X, Y) \xi = \eta(Y) X - \eta(X) Y, \forall X, Y \in \chi(\mathbf{M}).$$

In a Sasakian manifold equipped with the structure (ϕ, ξ, η, g) , the following relations also hold ([4, 13, 16]):

(2.2)
$$(\nabla_X \eta) Y = g(X, \phi Y), R(\xi, X)Y = g(X, Y)\xi - \eta(Y)X$$

 $S(X,\xi) = (n-1)\eta(X), R(X,\xi)Y = \eta(Y)X - g(X,Y)\xi$
 $Q\xi = (n-1)\xi, S(X,Y) = g(QX,Y).$

Using (2.1) and (2.2) in (1.2), we get

(2.3)
$$\overline{\nabla}_X Y = \nabla_X Y + g(X, \phi Y)\xi + \eta(Y)\phi X + \eta(X)\phi Y$$

with torsion tensor $\overline{T}(X, Y) = 2g(X, \phi Y)\xi$.

Proposition 2.1. Zamkovoy connection on Sasakian manifold is a metric connection and its torsion is of the form $\overline{T}(X,Y) = 2g(X,\phi Y)\xi$.

Proposition 2.2. In Sasakian manifold ξ and g are parallel with respect to Zamkovoy connection.

Proposition 2.3. In Sasakian manifold integral curve of ξ is a geodesic with respect to Zamkovoy connection.

3. Some properties of Sasakian manifold admitting Zamkovoy connection

Let \overline{R} denote the Riemannian curvature tensor with respect to Zamkovoy connection, defined as:

$$\overline{R}(X,Y)Z = \overline{\nabla}_X \overline{\nabla}_Y Z - \overline{\nabla}_Y \overline{\nabla}_X Z - \overline{\nabla}_{[X,Y]} Z,$$

for all $X, Y, Z \in \chi(\mathbf{M})$.

By the help of (2.3), (2.1), and the above equation, we get the Riemannian curvature tensor with respect to Zamkovoy connection as

(3.1)

$$R(X,Y) Z = R(X,Y) Z - g(Z,\phi X) \phi Y - g(Y,\phi Z) \phi X$$

$$- 2g(Y,\phi X) \phi Z + g(X,Z) \eta(Y) \xi - \eta(X) g(Y,Z) \xi$$

$$+ \eta(X) \eta(Z) Y - \eta(Y) \eta(Z) X.$$

Consequently, one can easily bring out the following results:

(3.2)
$$\overline{S}(Y,Z) = S(Y,Z) + 2g(Y,Z) - (1+n)\eta(Y)\eta(Z)$$

(3.3)
$$\overline{S}(Y,\xi) = 0 = \overline{S}(\xi,Z)$$

(3.4)
$$\overline{Q}Y = QY + 2Y - (1+n)\eta(Y)\xi , \ \overline{Q}\xi = 0$$

$$(3.5) \overline{r} = r+n-1$$

(3.6)
$$\overline{R}(X,Y)\xi = 0, \overline{R}(\xi,Y)Z = 0, \overline{R}(X,\xi)Z = 0$$

Proposition 3.1. Let M be an *n*-dimensional Sasakian manifold admitting Zamkovoy connection $\overline{\nabla}$, Then

- (i) The curvature tensor \overline{R} of $\overline{\nabla}$ is given by (3.1)
- (*ii*) The Ricci tensor \overline{S} of $\overline{\nabla}$ is given by (3.2)
- (*iii*) The scalar curvature \overline{r} of $\overline{\nabla}$ is given by (3.5)
- (iv) The Ricci tensor \overline{S} of $\overline{\nabla}$ is symmetric.

Theorem 3.1. If a Sasakian manifold M is Ricci flat with respect to the Zamkovoy connection, then M is an η -Einstein manifold.

Proof. Suppose that the Sasakian manifold is Ricci flat with respect to the Zamkovoy connection. Then from (3.2), we get

$$S(Y,Z) = -2g(Y,Z) + (1+n)\eta(Y)\eta(Z).$$

Which shows that M is an η -Einstein manifold.

4. M-projectively flat Sasakian manifold with respect to the Zamkovoy connection $\overline{\nabla}$

Theorem 4.1. A *M*-projectively flat Sasakian manifold **M** (n > 2) admitting Zamkovoy connection $\overline{\nabla}$ is an η -Einstein manifold.

Proof. Let M be an n- dimensional M-projectively flat Sasakian manifold with respect to Zamkovoy connection, i.e $\overline{M} = 0$, then from (1.3) we have

(4.1)
$$\overline{R}(X,Y)Z = \frac{1}{2(n-1)} \left[\overline{S}(Y,Z)X - \overline{S}(X,Z)Y\right] + \frac{1}{2(n-1)} \left[g(Y,Z)\overline{Q}X - g(X,Z)\overline{Q}Y\right].$$

Taking inner product with a vector field V in (4.1), we get

$$\overline{R}(X, Y, Z, V) = \frac{1}{2(n-1)} \left[\overline{S}(Y, Z) g(X, V) - \overline{S}(X, Z) g(Y, V) \right] + \frac{1}{2(n-1)} \left[g(Y, Z) \overline{S}(X, V) - g(X, Z) \overline{S}(Y, V) \right].$$

Taking a frame field of M, and contracting over X and V, we get

(4.2)
$$n\overline{S}(Y,Z) = g(Y,Z)\overline{r}$$

Using (3.2), (3.5) in (4.2), we get

$$S(Y,Z) = \frac{1}{n} (r - n - 1) g(Y,Z) + (1 + n) \eta(Y) \eta(Z)$$

Therefore, M is an η -Einstein manifold.

Theorem 4.2. A $\xi - M$ -projectively flat Sasakian manifold \mathbf{M} (n > 2) admitting Zamkovoy connection $\overline{\nabla}$ is an η -Einstein manifold.

Proof. If M (n > 2) be $\xi - M$ -Projectively flat with respect to Zamkovoy connection, i.e $\overline{M}(X, Y) \xi = 0$ then (1.3) gives

$$0 = \overline{M}(X, Y)\xi = \eta(Y)\overline{Q}X - \eta(X)\overline{Q}Y.$$

Now, taking inner product with a vector field V, we get

(4.3) $0 = \eta(Y)\overline{S}(X,V) - \eta(X)\overline{S}(Y,V).$

Setting $Y = \xi$ and using (3.2), (3.3) in (4.3), we have

(4.4)
$$S(X,V) = -2g(X,V) + (1+n)\eta(X)\eta(V)$$

Therefore, M is an η -Einstein manifold.

Corollary 4.1. If a Sasakian manifold M (n > 2) admitting Zamkovoy connection $\overline{\nabla}$ is $\xi - M$ -projectively flat then its scalar curvature is constant.

Let $\{e_i\}$ $(1 \le i \le n)$ be an orthonormal basis of the tangent space at any point of the manifold M. Then putting $Y = Z = e_i$ in the equation (4.4) and taking summation over i, $1 \le i \le n$, we get: r = -(n-1) = Constant.

Theorem 4.3. An *n*-dimensional Sasakian manifold is $\xi - M$ -projectively flat with respect to Zamkovoy connection iff it is so with respect to Levi-Civita connection, provided that the vector fields are horizontal vector fields.

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Proof. From (1.1), (1.3), (3.2) and (3.4), we get

$$\overline{M}(X,Y)Z = M(X,Y)Z - g(Z,\phi X)\phi Y - g(Y,\phi Z)\phi X - 2g(Y,\phi X)\phi Z + g(X,Z)\eta(Y)\xi - \eta(X)g(Y,Z)\xi + \eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X - \frac{1}{2(n-1)}[4g(Y,Z)X - 4g(X,Z)Y] + \frac{(1+n)}{2(n-1)}[\eta(Y)\eta(Z)X - \eta(X)\eta(Z)Y] + \frac{1}{2(n-1)}[(1+n)g(Y,Z)\eta(X)\xi - (1+n)g(X,Z)\eta(Y)\xi].$$

Setting $Z = \xi$ in (4.5) we have

(4.6)
$$\overline{M}(X,Y)\xi = M(X,Y)\xi + \eta(X)Y - \eta(Y)X + \frac{(n-3)}{2(n-1)}[\eta(X)Y - \eta(Y)X].$$

If *X* and *Y* are horizontal vector fields then from (4.6), it follows that $\overline{M}(X,Y)\xi = M(X,Y)\xi$. Hence, the theorem.

5. $\phi-M\mbox{-}P\mbox{rojectively flat}$ Sasakian manifold with respect to the connection $\overline{\nabla}$

Theorem 5.1. A ϕ -*M*-projectively flat Sasakian manifold **M** (n > 2) admitting Zamkovoy connection is an η -Einstein manifold.

We assume that a Sasakian manifold $\mathbf{M}(n > 2)$ is $\phi - M$ -Projectively flat with respect to Zamkovoy connection, i.e, $g(\overline{M}(\phi X, \phi Y) \phi Z, \phi V) = 0$, for all $X, Y, Z, V \in \chi(\mathbf{M})$. Then, in view of (1.3), we have

(5.1)

$$0 = \overline{R} (\phi X, \phi Y, \phi Z, \phi V) - \frac{1}{2(n-1)} \left[\overline{S} (\phi Y, \phi Z) g (\phi X, \phi V) - \overline{S} (\phi X, \phi Z) g (\phi Y, \phi V) \right] - \frac{1}{2(n-1)} \left[g (\phi Y, \phi Z) \overline{S} (\phi X, \phi V) - g (\phi X, \phi Z) \overline{S} (\phi Y, \phi V) \right],$$

where $\overline{R}(\phi X, \phi Y, \phi Z, \phi V) = g(\overline{R}(\phi X, \phi Y) \phi Z, \phi V)$.

Let $\{e_i, \xi\}$ $(1 \le i \le n-1)$ be a local orthonormal basis of the tangent space at any point of the manifold M. Using the fact that $\{\phi e_i, \xi\}$, $(1 \le i \le n-1)$ is also

a local orthonormal basis and setting $X = V = e_i$ and taking summation over $i(1 \le i \le n-1)$ in (5.1), we get

$$0 = \sum_{i=1}^{n-1} \overline{R} \left(\phi e_i, \phi Y, \phi Z, \phi e_i \right)$$

$$- \frac{1}{2(n-1)} \left[\sum_{i=1}^{n-1} \overline{S} \left(\phi Y, \phi Z \right) g \left(\phi e_i, \phi e_i \right) - \sum_{i=1}^{n-1} \overline{S} \left(\phi e_i, \phi Z \right) g \left(\phi Y, \phi e_i \right) \right]$$

$$- \frac{1}{2(n-1)} \left[\sum_{i=1}^{n-1} g \left(\phi Y, \phi Z \right) \overline{S} \left(\phi e_i, \phi e_i \right) - \sum_{i=1}^{n-1} g \left(\phi e_i, \phi Z \right) \overline{S} \left(\phi Y, \phi e_i \right) \right].$$

From which we obtain: $S(Y,Z) = \left[\frac{n-r+3}{n+1}\right]g(Y,Z) + \left[\frac{n^2-n+r-4}{n+1}\right]\eta(Y)\eta(Z)$. Therefore, M is an η -Einstein manifold.

6. Locally M-Projectively ϕ -symmetric Sasakian manifolds admitting Zamkovoy connection

The notion of local ϕ -symmetry for Sasakian manifolds was introduced by Takahashi [15]. In this section we consider a locally M-Projectively ϕ -symmetric Sasakian manifolds with respect to Zamkovoy connection.

Definition 6.1. A Sasakian manifold **M** is said to be locally M-Projectively ϕ -symmetric with respect to Zamkovoy connection $\overline{\nabla}$ if the M-Projective curvature tensor with respect to Zamkovoy connection satisfies: $\phi^2(\overline{\nabla}_V \overline{M})(X,Y)Z = 0$, where X, Y, Z and V are horizontal vector fields on **M**.

Theorem 6.1. A Sasakian manifold \mathbf{M} (n > 2) is locally *M*-projectively ϕ -symmetric with respect to Zamkovoy connection iff it is so with respect to Levi-Civita connection.

Proof. In view of (2.3), we have

(6.1)
$$(\overline{\nabla}_V \overline{M}) (X, Y) Z = (\nabla_V \overline{M}) (X, Y) Z + g (V, \phi \overline{M} (X, Y) Z) \xi + \eta (\overline{M} (X, Y) Z) \phi V + \eta (V) \phi \overline{M} (X, Y) Z.$$

Taking covariant derivative of (4.5), in the direction of V, we get

(6.2)
$$\left(\nabla_V \overline{M}\right)(X,Y)Z = \left(\nabla_V M\right)(X,Y)Z.$$

Taking inner product of (4.5) with ξ , we get

(6.3)

$$\eta \left(\overline{M} (X, Y) Z \right) = \eta \left(M (X, Y) Z \right) + g (X, Z) \eta (Y) - \eta (X) g (Y, Z) + \frac{(n-3)}{2(n-1)} \left[4g (Y, Z) \eta (X) - 4g (X, Z) \eta (Y) \right].$$

Using (6.2), (6.3) in (6.1), and applying ϕ^2 on both sides, we have: $\phi^2(\overline{\nabla}_V \overline{M})$ $(X, Y) Z = \phi^2(\nabla_V M)(X, Y) Z$, where X, Y, Z and V are horizontal vector fields on M. The last equation shows that the locally M-Projectively ϕ -symmetries in Sasakian manifold with respect to Zamkovoy connection $\overline{\nabla}$ and Levi-Civita connection ∇ are equivalent.

7. Sasakian manifold admitting Zamkovoy connection $\overline{\nabla}$ satisfying $\overline{M}(\xi, U) \circ \overline{R} = 0$

Theorem 7.1. In an *n*-dimensional (n > 2) Sasakian manifold M admitting Zamkovoy connection $\overline{\nabla}$, if the condition $\overline{M}(\xi, U) \circ \overline{R} = 0$ holds, then the equation: $S^{2}(Y, U) = -4S(Y, U) - 4g(Y, U) + (1 + n)^{2} \eta(Y) \eta(U)$ is satisfied on M.

Proof. We consider a Sasakian manifold M satisfying the condition:

$$\left(\overline{M}\left(\xi,U\right)\circ\overline{R}\right)\left(X,Z\right)V=0,$$

where \overline{M} , \overline{R} are M-Projective curvature tensor and Riemannian curvature tensor with respect to Zamkovoy connection respectively and $U, Y, Z \in \chi(\mathbf{M})$. Then, we have

$$\overline{M}(\xi, U) \overline{R}(X, Z) V = \overline{R} \left(\overline{M}(\xi, U) X, Z \right) V + \overline{R} \left(X, \overline{M}(\xi, U) Z \right) V + \overline{R}(X, Z) \overline{M}(\xi, U) V.$$

Replacing *X* by ξ and using (3.6), we get

(7.1)
$$0 = \overline{R} \left(\overline{M} \left(\xi, U \right) \xi, Z \right) V.$$

By the help of (1.3),(3.6) and (7.1), we get: $\overline{R}(QU,Z)V + 2\overline{R}(U,Z)V = 0$.

Taking inner product with Y in the above equation and considering a frame field of \mathbf{M} , and contracting over Z and V, we get

$$S^{2}(Y,U) = -4S(Y,U) - 4g(Y,U) + (1+n)^{2} \eta(Y) \eta(U).$$

Hence, the theorem is proved.

8. EXAMPLE OF 5-DIMENSIONAL SASAKIAN MANIFOLD ADMITTING ZAMKOVOY CONNECTION.

Consider 5-dimensional manifold $\mathbf{M}^5 = \{(x, y, z, u, v) \in \mathbb{R}^5\}$, where (x, y, z, u, v) are the std. co-ordinates in \mathbb{R}^5

We choose the linearly independent vector fields $I_1 = e^z \frac{\partial}{\partial x}$, $I_2 = e^z \frac{\partial}{\partial y}$, $I_3 = \frac{\partial}{\partial z}$, $I_4 = e^z \frac{\partial}{\partial u}$, $I_5 = e^z \frac{\partial}{\partial v}$.

Let g be the Riemannian metric defined by $g(I_i, I_j) = 0$, if $i \neq j$ and $g(I_i, I_j) = 1$, if i = j, for i, j = 1, 2, 3, 4, 5.

Let η be the 1 - form defined by $\eta(X) = g(X, I_3)$ for any $X \in \chi(\mathbf{M}^5)$. Let ϕ be the (1, 1) tensor field defined by:

 $\phi I_1 = I_1, \phi I_2 = I_2, \phi I_3 = 0, \phi I_4 = I_4, \phi I_5 = I_5.$ Let $X, Y, Z \in \chi$ (M⁵) be given by

$$\begin{aligned} X &= x_1 I_1 + x_2 I_2 + x_3 I_3 + x_4 I_4 + x_5 I_5, \\ Y &= y_1 I_1 + y_2 I_2 + y_3 I_3 + y_4 I_4 + y_5 I_5, \\ Z &= z_1 I_1 + z_2 I_2 + z_3 I_3 + z_4 I_4 + z_5 I_5. \end{aligned}$$

Then we have

 $g(X,Y) = x_1y_1 + x_2y_2 + x_3y_3 + x_4y_4 + x_5y_5, \eta(X) = x_3,$

 $g(\phi X, \phi Y) = x_1 y_1 + x_2 y_2 + x_4 y_4 + x_5 y_5.$

Using the linearity of g and ϕ , we get: $\eta(I_3) = 1, \phi^2 X = -X + \eta(X) I_3$ and $g(\phi X, \phi Y) = g(X, Y) - \eta(X) \eta(Y)$ for all $X, Y \in \chi(M^5)$.

We have: $[I_1, I_3] = -I_1, [I_2, I_3] = -I_2, [I_4, I_3] = -I_4, [I_5, I_3] = -I_5$ and $[\epsilon_I, \epsilon_j] = 0$ for all others *I* and *j*.

Let the Levi-Civita connection with respect to g be ∇ , then using Koszul formula we get the following

$$\begin{split} \nabla_{_{I_1}}I_1 &= I_3, \nabla_{_{I_1}}I_3 = -I_1, \nabla_{_{I_2}}I_2 = I_3, \nabla_{_{I_2}}I_3 = -I_2, \nabla_{_{I_4}}I_3 = -I_4, \\ \nabla_{_{I_4}}I_4 &= I_3, \nabla_{_{I_5}}I_3 = -I_5, \nabla_{_{I_5}}I_5 = I_3. \end{split}$$

From the above results we see that the structure (ϕ, ξ, η, g) satisfies: $(\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X, \forall X, Y \in \chi(M^5)$, where $\eta(\xi) = \eta(I_3) = 1$. Hence (ϕ, ξ, η, g) is a Sasakian structure and $M^5(\phi, \xi, \eta, g)$ is a 5-dimensional Sasakian manifold.

The non zero components of Riemannian curvature with respect to Levi-Civita connection ∇ are given by:

$$\begin{split} &R\left(I_{1},I_{2}\right)I_{1}=I_{2},R\left(I_{1},I_{2}\right)I_{2}=-I_{1},R\left(I_{1},I_{3}\right)I_{1}=I_{3},R\left(I_{1},I_{3}\right)I_{3}=-I_{1}\\ &R\left(I_{1},I_{4}\right)I_{1}=I_{4},R\left(I_{1},I_{4}\right)I_{4}=-I_{1},R\left(I_{1},I_{5}\right)I_{1}=I_{5},R\left(I_{1},I_{5}\right)I_{5}=-I_{1}\\ &R\left(I_{2},I_{1}\right)I_{2}=I_{1},R\left(I_{2},I_{1}\right)I_{1}=-I_{2},R\left(I_{2},I_{3}\right)I_{2}=I_{3},R\left(I_{2},I_{3}\right)I_{3}=-I_{2}\\ &R\left(I_{2},I_{4}\right)I_{2}=I_{4},R\left(I_{2},I_{4}\right)I_{4}=-I_{2},R\left(I_{2},I_{5}\right)I_{2}=I_{5},R\left(I_{2},I_{5}\right)I_{5}=-I_{2} \end{split}$$

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$$\overline{\nabla}_{I_1} I_1 = 2I_3, \overline{\nabla}_{I_2} I_2 = 2I_3, \overline{\nabla}_{I_3} I_1 = I_1, \overline{\nabla}_{I_3} I_2 = I_2$$
$$\overline{\nabla}_{I_3} I_4 = I_4, \overline{\nabla}_{I_3} I_5 = I_5, \overline{\nabla}_{I_4} I_4 = 2I_3, \overline{\nabla}_{I_5} I_5 = 2I_3$$

The non zero components of Riemannian curvature tensor with respect to Zamkovoy connection are given by

$$\overline{R} (I_1, I_3) I_1 = 4I_3, \overline{R} (I_2, I_3) I_2 = 4I_3, \overline{R} (I_4, I_3) I_4 = 4I_3, \\ \overline{R} (I_5, I_3) I_5 = 4I_3, \overline{R} (I_3, I_1) I_1 = -4I_3, \overline{R} (I_3, I_2) I_2 = -4I_3$$

Using the above curvature tensors the Ricci tensors with respect to ∇ and ∇^* are: $S(I_1, I_1) = S(I_2, I_2) = S(I_3, I_3) = S(I_4, I_4) = S(I_5, I_5) = -4$. The relation between two scalar curvatures \overline{r} and r in M^5 is obtained as follows $\overline{r} = \sum_{I=1}^{5} \overline{S}(I_i, I_i) = -16 = \sum_{I=1}^{5} S(I_i, I_i) + 5 - 1 = r + n - 1$, which implies the relation (3.5). Similarly, all the results can be verified.

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DEPARTMENT OF MATHEMATICS RAIGANJ SURENDRANATH MAHAVIDYALAYA RAIGANJ, UTTAR DINAJPUR, WEST BENGAL, INDIA *Email address*: abhijit4791@gmail.com

DEPARTMENT OF MATHEMATICS RAIGANJ UNIVERSITY RAIGANJ, UTTAR DINAJPUR, WEST BENGAL, INDIA *Email address*: ashoke.avik@gmail.com